

Substitute for form 1449A/PTO

**INFORMATION DISCLOSURE
STATEMENT BY APPLICANT**

(use as many sheets as necessary)

Sheet

1

of

8

Complete if Known

Application Number	10/737,195
Filing Date	December 15, 2003
First Named Inventor	WANG, YULUN
Art Unit	3739
Examiner Name	Unassigned
Attorney Docket Number	022001-000843US

U.S. PATENT DOCUMENTS+

Examiner Initials*	Cite No. ¹	Document Number	Publication Date MM-DD-YYYY	Name of Patentee or Applicant of Cited Document	Pages, Columns, Lines, Where Relevant Passages or Relevant Figures Appear
		Number Kind Code ² (if known)			
dr	AA	977,825	12-06-1910	Murphy	
	AB	3,171,549	03-02-1965	Orloff	
	AC	3,280,991	10-25-1966	Melton et al.	
	AD	4,058,001	11-15-1977	Waxman	
	AE	4,128,880	12-05-1978	Cray, Jr.	
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	AL	4,503,854	03-12-1985	Jako	
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	AW	4,672,963	06-16-1987	Barken	
	AX	4,676,243	06-30-1987	Clayman	
	AY	4,728,974	03-01-1988	Nio et al.	
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	BA	4,791,934	12-20-1988	Brunnett	
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	BH	4,854,301	08-08-1989	Nakajima	
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	BN	4,949,717	08-21-1990	Shaw	
	BO	4,965,417	10-23-1990	Massie	

Examiner
Signature

J. LEUBACKER

Date
Considered

10/31/05

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			Examiner Name	Unassigned	
Sheet	2	of	8	Attorney Docket Number	022001-000843US

U.S. PATENT DOCUMENTS+					
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		Number Kind Code ² (if known)			
J	BP	4,969,709	11-13-1990	Sogawa et al.	
	BQ	4,969,890	11-13-1990	Sugita et al.	
	BR	4,979,933	12-25-1990	Runge	
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	BV	5,020,001	05-28-1991	Yamamoto et al.	
	BW	5,065,741	11-19-1991	Uchiyama et al.	
	BX	5,078,140	01-07-1992	Kwoh	
	BY	5,086,401	02-04-1992	Glassman et al.	
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	CA	5,097,829	03-24-1992	Quisenberry	
	CB	5,097,839	03-24-1992	Allen	
	CC	5,098,426	03-24-1992	Sklar et al.	
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	CS	5,221,283	06-22-1993	Chang	
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	CX	5,257,999	11-02-1993	Slanetz, Jr.	
	CY	5,271,384	12-21-1993	McEwen et al.	
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	DC	5,289,365	02-22-1994	Caldwell et al.	
	DD	5,299,288	03-29-1994	Glassman et al.	
Examiner Signature	J. Leubke			Date Considered	10/31/05

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		Number Kind Code ² (if known)			
	DE	5,300,926	04-05-1994	Stoeckl	
	DF	5,303,148	04-12-1994	Mattson et al.	
	DG	5,304,185	04-19-1994	Taylor	
	DH	5,305,203	04-19-1994	Raab	
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	DQ	5,345,538	09-06-1994	Narayannan et al.	
	DR	5,368,015	11-29-1994	Wilk	
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	DW	5,402,801	04-04-1995	Taylor	
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	DZ	5,410,638	04-25-1995	Colgate et al.	
	EA	5,417,210	05-23-1995	Funda et al.	
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	EI	5,455,766	10-03-1995	Scheller et al.	
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	ES	5,609,560	03-11-1997	Ichikawa et al.	

Examiner Signature	<i>J. LAUBCKER</i>	Date Considered	10/31/05
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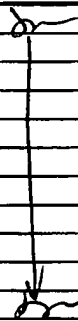
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		Art Unit	3739		
		Examiner Name	Unassigned		
Sheet	4	of	8	Attorney Docket Number	022001-000843US

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		Number Kind Code ² (if known)			
	ET	5,626,595	05-06-1997	Sklar et al.	
	EU	5,629,594	05-13-1997	Jacobus et al.	
	EV	5,630,431	05-20-1997	Taylor	
	EW	5,631,973	05-20-1997	Green	
	EX	5,636,259	06-03-1997	Khutoryansky et al.	
	EY	5,657,429	08-12-1997	Wang et al.	
	EZ	5,658,250	08-19-1997	Blomquist et al.	
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	FD	5,698,837	12-09-1997	Green	
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	FF	5,737,711	04-07-1998	Abe	
	FG	5,749,362	05-12-1998	Funda et al.	
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	FI	5,766,126	06-16-1998	Anderson	
	FJ	5,779,623	07-14-1998	Bonnell	
	FK	5,800,423	09-01-1998	Jensen	
	FL	5,807,284	09-15-1998	Foxlin	
	FM	5,807,378	09-15-1998	Jensen et al.	
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	FO	5,810,880	09-22-1998	Jensen et al.	
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	FV	5,855,583	01-05-1999	Wang et al.	
	FW	5,859,934	01-12-1999	Green	
	FX	5,860,995	01-19-1999	Berkelaar	
	FY	5,876,325	03-02-1999	Mizuno et al.	
	FZ	5,878,193	03-02-1999	Wang et al.	
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	GF	6,102,850	08-15-2000	Wang et al.	
	GG	2002/0140665	10-03-2002	Gordon	
Examiner Signature	J. LUBBECKER		Date Considered	10/31/05	

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		Country Code ²	Number ⁴	Kind Code ⁵ (if known)				
	GH	DE	92 04 118.3		07-02-1992			<input type="checkbox"/>
	GI	EP	0239409	A1	09-30-1987			<input type="checkbox"/>
	GJ	EP	0424687	A1	05-02-1991			<input type="checkbox"/>
	GK	EP	A-0494943		Aug., 1995			<input type="checkbox"/>
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	GR	WO	98/25666		06-18-1998			<input type="checkbox"/>

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NON PATENT LITERATURE DOCUMENTS			
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	GS	ABSTRACT of a presentation "3-D Vision Technology Applied to Advanced Minimally Invasive Surgery Systems" given at the 3rd World Congress of Endoscopic Surgery in Bordeaux, (18 to 20 June 1992), entitled "Session 15/3" (1 page total).	
	GT	ABSTRACT of a presentation "A Pneumatic Controlled Sewing Device for Endoscopic Application the MIS Sewing Instrument MSI" given at the 3rd World Congress of Endoscopic Surgery in Bordeaux, June 18-20, 1992 (1 page total).	
	GU	ABSTRACT of a presentation "Concept and Experimental Application of a Surgical Robotic System the Steerable MIS Instrument SMI" given at the 3rd World Congress of Endoscopic Surgery in Bordeaux, June 18-20, 1992 (1 page total).	
	GV	ABSTRACT of a presentation given at the 3rd World Congress of Endoscopic Surgery in Bordeaux (18 to 20 June 1992), entitled "Session 15/2" (1 page total).	
	GW	ABSTRACT of a presentation given at the 3rd World Congress of Endoscopic Surgery in Bordeaux (18 to 20 June 1992), entitled "Session 15/5" (1 page total).	
	GX	ABSTRACT of a presentation given at the 3rd World Congress of Endoscopic Surgery in Bordeaux (18 to 20 June 1992), entitled "Session 15/4" (1 page total).	
	GY	ABSTRACT of a presentation given at the 3rd World Congress of Endoscopic Surgery in Bordeaux, (18 to 20 June 1992), entitled "Session 15/1" (1 page total).	
	GZ	BEJCZY, "Controlling Remote Manipulators through Kinesthetic Coupling," Computers in Mechanical Engineering 1983, pp. 48-60.	
	HA	BESANT et al., Abstract of a presentation "Camera Control for Laparoscopic Surgery by Speech-Recognizing Robot: Constant Attention and Better Use of Personnel," given at the 3rd World Congress of Endoscopic Surgery in Bordeaux, June 18-20, 1992 (1 page total).	
	HB	CHARLES et al., "Design of a Surgeon-Machine Interface for Teleoperated Microsurgery," IEEE 1989 (3 pages total).	
	HC	COLGATE, "Power and Impedance Scaling in Bilateral Manipulation," IEEE, 1991, pp. 2292-2297.	
	HD	CORCORAN, "Robots for the Operating Room," The New York Times, Sunday July 19, 1992, Section 3, Page 9, Column 1 (2 pages total).	
	HE	DAS et al., "Kinematic Control and Visual Display of Redundant Teleoperators," IEEE 1989 pp. 1072-1077.	
	HF	DOLAN et al., "A Robot in an Operating Room: A Bull in a China Shop," IEEE, 1987, pp. 1096-1097.	
	HG	GAYED et al., "An Advanced Control Micromanipulator for Surgical Applications," Systems Science Vol. 13, 1987, pp. 23-34.	

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NON PATENT LITERATURE DOCUMENTS			
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✓	HH	GREEN et al., Abstract of a presentation "Telepresence: Advanced Teleoperator Technology for Minimally Invasive Surgery," given at "Medicine meets virtual reality" symposium in San Diego, June 4-7, 1992 (20 pages total).	
	HI	GREEN et al., Abstract of a presentation "Telepresence: Advanced Teleoperator Technology for Minimally Invasive Surgery," given at the 3rd World Congress of Endoscopic Surgery in Bordeaux, June 18-20, 1992 (2 pages total).	
	HJ	GREEN, Statutory Declaration of Dr. Philip S. Green, presenter of the video entitled "Telepresence Surgery - The Future of Minimally Invasive Medicine" (32 page total).	
	HK	GUERROUAD et al., "S.M.O.S.: Stereotaxical Microtelemanipulator for Ocular Surgery," IEEE, 1989, pp. 879-880.	
	HL	Inoue, "Force Feedback-Based Telemicromanipulation for Robot Surgery on Soft Tissues" (A.M. Inoue), IEEE 1989.	
	HM	INQUE et al., "Six-axis Bilateral Control of an Articulated Slave Manipulator Using a Cartesian Master Manipulator," Advanced Robotics, 4, No. 2, 1990, pp. 139-150.	
	HN	KAZEROONI, "Human/Robot Interaction via the Transfer of Power and Information Signals - Part I: Dynamics and Control Analysis," IEEE, 1989, pp. 1632-1640.	
	HO	KAZEROONI, "Human/Robot Interaction via the Transfer of Power and Information Signals - Part II: An Experimental Analysis," IEEE, 1989, pp. 1641-1647.	
	HP	KRISHNAN et al., Abstract of a presentation "Design Considerations of a New Generation Endoscope Using Robotics and Computer Vision Technology," given at the 3rd World Congress of Endoscopic Surgery in Bordeaux, June 18-20, 1992 (1 page total).	
	HQ	LAVALLEE, "A New System for Computer Assisted Neurosurgery," IEEE, 1989, vol.11, pp. 926-927.	
	HR	MAIR, Industrial Robotics, Prentice Hall, 1988, pp. 41-43, 49-50, 54, 203-209.	
	HS	MAJIMA et al., "On a Micro-Manipulator for Medical Application - Stability Consideration of its Bilateral Controller," Mechatronics, 1991, pp. 293-309.	
	HT	NASA, "Anthropomorphic Remote Manipulator", NASA Tech Briefs, 1991 (1 page total).	
	HU	PREISING et al., "A Literature Review: Robots in Medicine," IEEE, June 1991, pp. 13-22 & 71.	
✓	HV	TAUBES, "Surgery in Cyberspace," Discover Magazine, December 1994, pp. 85-92.	
✓	HW	TAYLOR et al., "Taming the Bull: Safety in a Precise Surgical Robot," IEEE, 1991, pp. 865-871.	

Examiner Signature	J. LEBECKER	Date Considered	10/31/05
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* EXAMINER: Initial if reference considered, whether or not citation is in conformance with MPEP 609. Draw line through citation if not in conformance and not considered. Include copy of this form with next communication to applicant.

¹ Applicant's unique citation designation number (optional). ² Applicant is to place a check mark here if English language Translation is attached.

Substitute for form 1449B/PTO INFORMATION DISCLOSURE STATEMENT BY APPLICANT (use as many sheets as necessary)		Complete If Known			
		Application Number	10/737,195		
		Filing Date	December 15, 2003		
		First Named Inventor	WANG, YULUN		
		Art Unit	3739		
		Examiner Name	Unassigned		
Sheet	8	of	8	Attorney Docket Number	022001-000843US

NON PATENT LITERATURE DOCUMENTS			
Examiner Initials *	Cite No. ¹	Include name of the author (in CAPITAL LETTERS), title of the article (when appropriate), title of the item (book, magazine, journal, serial, symposium, catalog, etc.), date, page(s), volume-issue number(s), publisher, city and/or country where published.	T ²
	HX	TEJIMA, "A New Microsurgical Robot System for Corneal Transplantation," Precision Machinery, 1988 vol. 2, pp. 1-9.	
	HY	TENDICK et al., "Analysis of the Surgeon's Grasp for Telerobotic Surgical Manipulation," IEEE, 1989, pp. 914-915.	
	HZ	THRING, "Robots and Telechirs: Manipulator with Memory: Remote Manipulators: Machine Limbs for the Handicapped," Wiley & Sons, 1983 (26 pages total).	
	IA	Transcript of a video presented by SRI at the 3rd World Congress of Endoscopic Surgery in Bordeaux on June 18-20, 1992, in Washington on April 9, 1992, and in San Diego, CA on June 4-7, 1992 entitled "Telepresence Surgery - The Future of Minimally Invasive Medicine" (3 pages total).	
	IB	TREVELYAN et al., "Motion Control for a Sheep Shearing Robot," Proceedings of the 1st International Symposium on Robotics Research, MIT, Cambridge, Massachusetts, USA, 1983, pp.175-190.	
	IC	VIBET, "Properties of Master-Slave Robots," Motor-con, 1987, pp. 309-314.	
	ID	WOLF et al., "Student Reference Manual for Electronic Instrumentation Laboratories," Prentice Hall, New Jersey 1990, pp. 498-499.	

Examiner Signature		Date Considered	10/31/05
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